



AI FOR EO DATA PRODUCTION AND ANALYTICS

RESULTS AND PERSPECTIVES OF CNES' EO DEPARTMENT RESEARCH

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Outline

- Context of EO ground segments
- Presentation of image processing frameworks
- Selection of AI research lead by CNES
 - Analytics on VHR images (Quantcube, Irida)
 - Scheduling of processing chains (CapGemini)
 - Transfer learning for new EO missions (Thales Alenia Space, Irida)
 - Detection of clouds using traditional and AI techniques
- Conclusion and future work

Context for ground segment from CNES' perspective

Earth observation is changing

- Increased volume of data and providers
- New actors



Rethinking: data platform and services

- Copernicus and Collaborative GS → <http://peps.cnes.fr>
- ESA/EU: DIAS, TEP, MEP,
- Market Place business: Initiatives One Atlas and GBDX



A new business model:

- Users want more reactivity, data lifetime value is shortened
- Open data and open source
- Users want information!

Context for ground segment from CNES' perspective

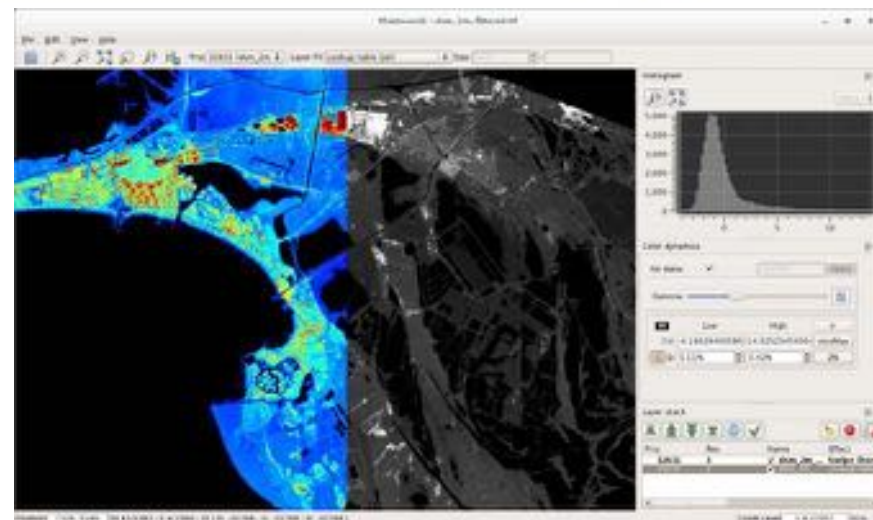
Data is a key element

- ❖ Big amount of EO data available at CNES
 - Sentinel 1,2,3 mirror of ESA
 - Pleiades data (limited to scientific usage)
 - Spot 1-5 archive (30 years)
 - Upcoming missions
- ❖ Current archive not entirely labeled
 - Permanently growing database





<https://www.orfeo-toolbox.org/>



- ❖ **Open-source** remote sensing image processing library
- ❖ Large community and easy to contribute: <https://www.orfeo-toolbox.org/community/>
- ❖ Image algorithms written in C++ and wrapped into OTB applications
- ❖ Easy to use and to incorporate into Python scripts: in-memory connection of OTB applications: <https://www.orfeo-toolbox.org/CookBook/recipes/python.html>

Image processing toolboxes

Important set of optimized and generic image processing libraries inherited from legacy missions

- ❖ Image resampling, deconvolution, denoising, etc.
- ❖ Sensor modeling (camera model)
- ❖ Correlation, image matching, image mosaicking, fusion
- ❖ Atmospheric corrections (joint algorithm CNES-DLR)
- ❖ Segmentation, Classification, 3D
- ❖ New: **Tensorflow-module**

Sub-set as open source library available on-line :

<https://www.orfeo-toolbox.org/>



Machine learning for analytics in VHR images

R&D project in progress

Main goal

- ❖ Count the number of vehicles in strategic locations using Deep Learning techniques and databases from various sensors (Pleiades, etc ...)



Challenges

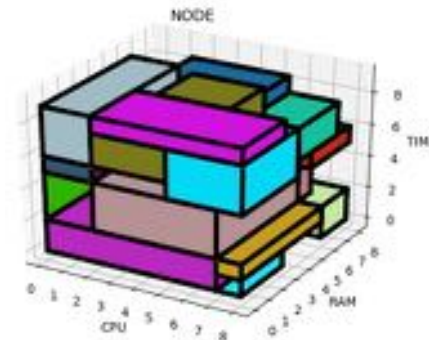
- ❖ Definition of strategic points in VHR images
- ❖ Constitution of the learning database
- ❖ Definition of the neural network architecture
- ❖ Generalization of the procedure (detection of planes, boats, etc.)
- ❖ Demonstration of maturity for an operational application



Illustration of car detection in parking lots with drones
© University of Vermont Spatial Analysis Laboratory

Machine Learning for performance optimization of processing chains

Completed R&D activity

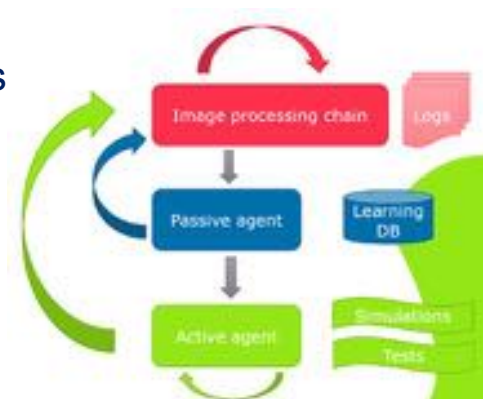


Main goal

- ❖ State-of-the-art of Machine Learning techniques for scheduling optimization with Reinforcement Learning
- ❖ Identification of available status (CPU, RAM, IO) and possible action (parameters)
- ❖ **AI** development to optimize orchestration and reduce production times
- ❖ Simulation strategies to explore optimal orchestrations

Results

- ❖ Successful implementation of genetic learning and reinforcement learning
- ❖ Compromise between generalization and learning time



Transfer learning

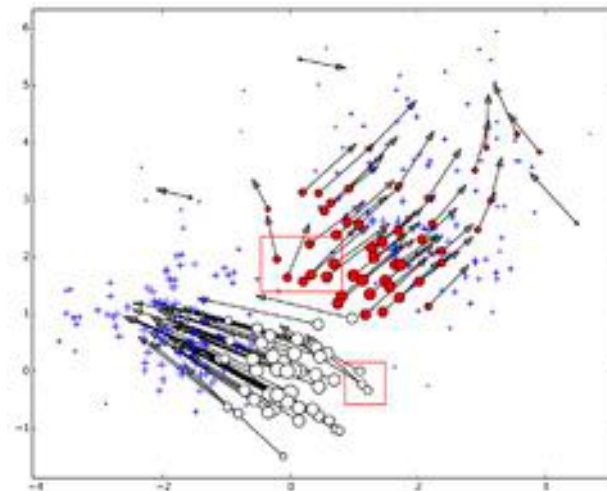
PhD work in progress (2018-2021)

Main goal

- ❖ Quantification of Deep Learning pros/cons vs. traditional methods
- ❖ Transfer learning to other sensors in order to obtain a fast and usable result at a lower cost
 - production of enriched data from the beginning of a new earth observation mission

Challenges

- ❖ Adapt Deep Learning models from one sensor to another (adaptation layers) and answer the question: How to transfer knowledge between different feature spaces?
- ❖ Improve the efficiency of current processing chains through the combined use of Deep Learning and traditional methods



Nicolas Courty © Irisa

Machine learning for cloud detection and transfer learning

Ongoing internal project

- ❖ Development of a new Deep Learning processing chain for cloud/snow/shadow detection in Sentinel-2 images
- ❖ Comparison with the output masks of MAJA

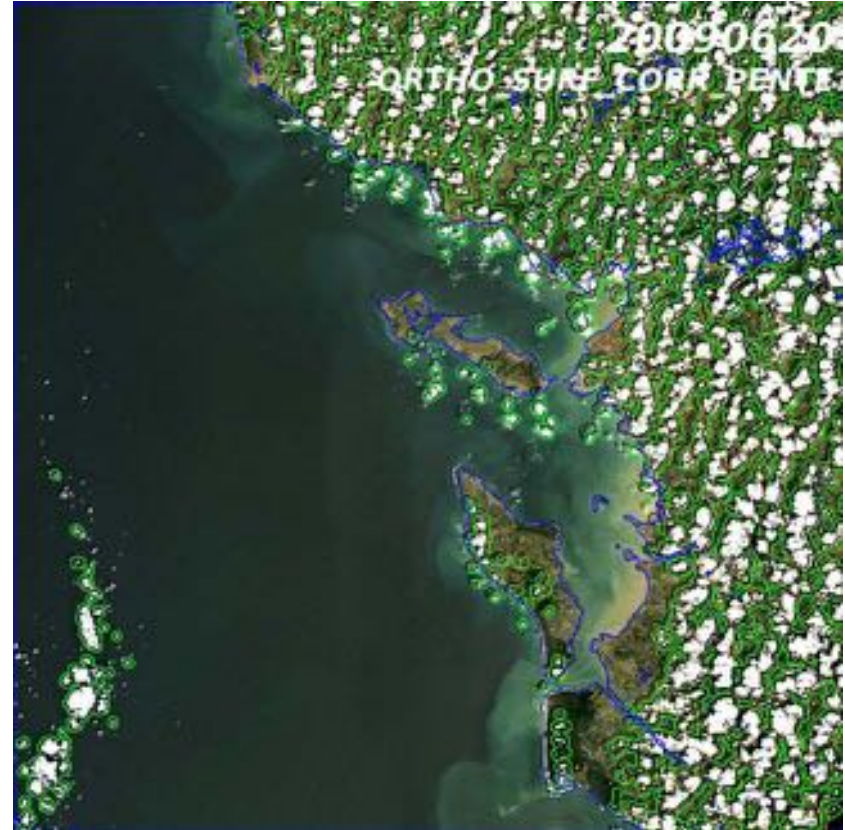


Illustration of cloud detection with MAJA on S2 images

© Cesbio

Cloud detection in detail

- ❖ Training, Validation and Comparison: MAJA's Level-2 cloud masks, coming from THEIA:



- ❖ Resampling of images to same resolution as MAJA (240m/120m) → Equal conditions
→ Total of 1000 Level-2 and Level-1 Sentinel-2 products available **daily**

Cloud detection in detail:

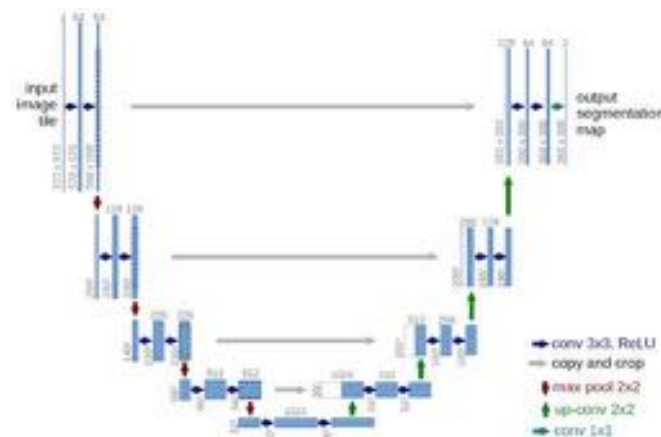
Creating an adaptable model

Different configurations for the output classes:

- ❖ Clouds (different types)
- ❖ Shadows (with and without)

Transfer learning approach

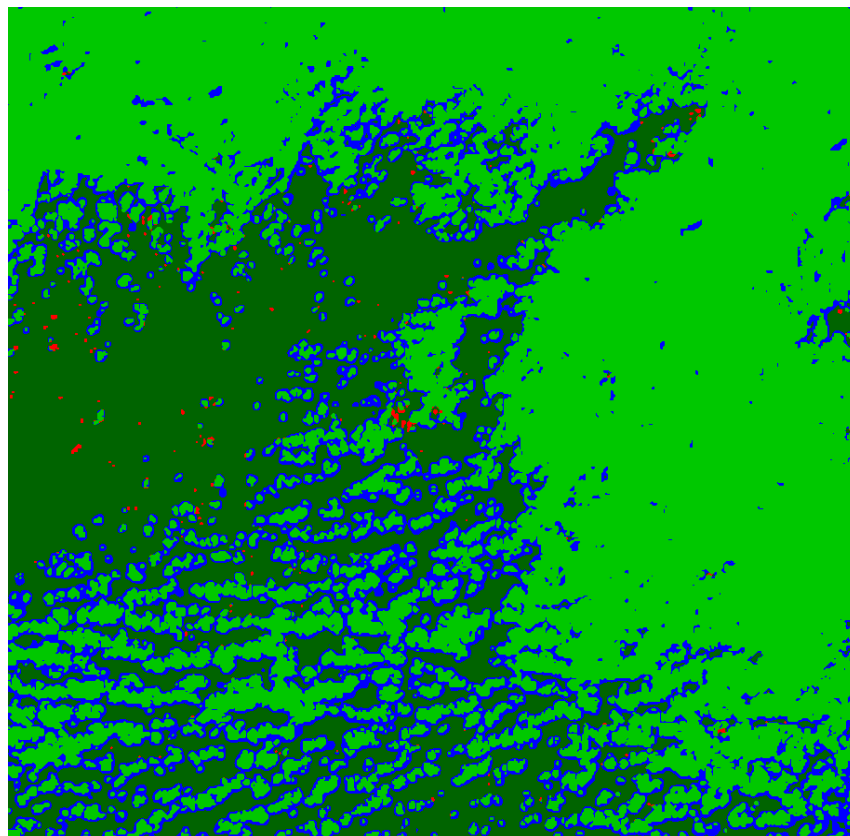
- ❖ Using existing models: Unet, VGG etc. → Variation with regularization techniques
- Current best F2-Score for single class (clouds): **91% (Unet)**
- **Usage of active learning for the future**



Unet illustration_© Uni Freiburg

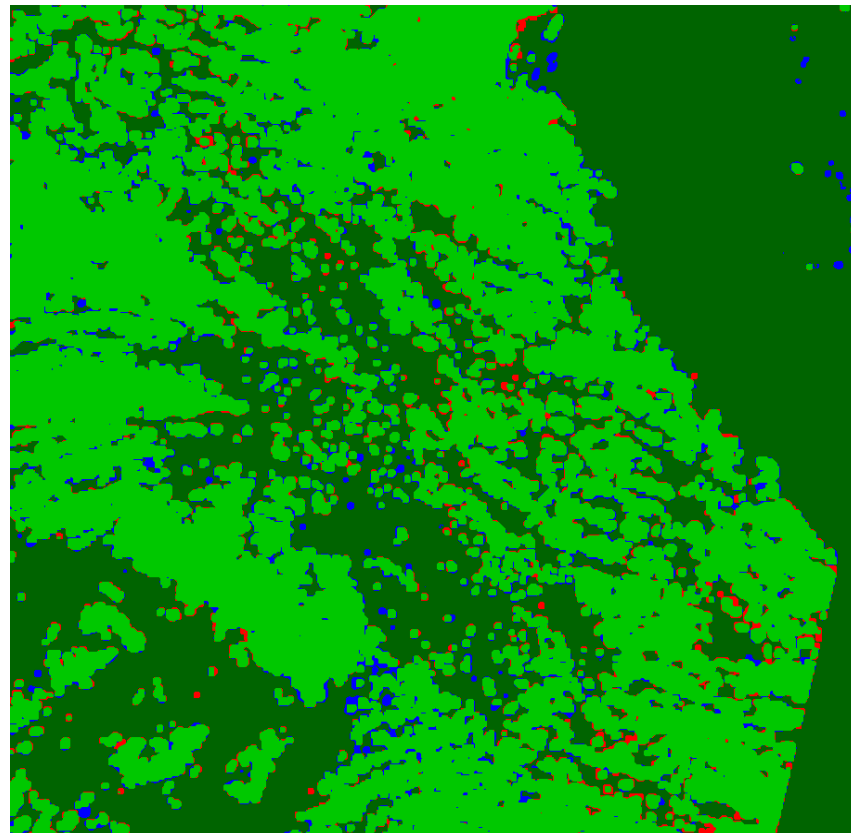
Cloud detection in detail

Cloud Clear Omission Overdetection



Cloud detection in detail

Cloud Clear Omission Overdetection



Conclusions and future work

Continuous researches together with industry, startups and academics

- ❖ Preparation of future EO missions and applications with innovative technologies
 - ❖ Deep Learning for analytics
 - ❖ Artificial intelligence combined with traditional approaches

Perspectives

- ❖ Validation of AI implementations for operational services
- ❖ Deployment on existing platforms (HPC, DIAS)

